## Recursive Blocked Algorithms for Solving Periodic Triangular Sylvester-type Matrix Equations

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Abstract. Recently, recursive blocked algorithms for solving one-sided and two-sided Sylvester-type equations were introduced [7–9]. This elegant yet simple technique enables an automatic variable blocking that has the potential of matching the memory hierarchies of today's HPC systems. The main parts of the computations are performed as level 3 general matrix multiply and add (GEMM) operations. In this presentation we extend our algorithms to also cover periodic Sylvester-type equations.

**Keywords:** Sylvester-type matrix equations, periodic matrix equations, recursion, level 3 BLAS, superscalar.

### 1 Introduction

In this presentation, we continue our work by developing algorithms for solving periodic Sylvester-type equations using recursion. One such example is the *periodic Sylvester equation* 

$$A_k X_k - X_{k+1} B_k = C_{k+1}, \quad k = 1, \dots, p-1$$
  
 $A_p X_p - X_1 B_p = C_1,$ 

where p is the periodicity of the matrix sequences, such that  $A_{k+p} = A_k, B_{k+p} = B_k$  and  $C_{k+p} = C_k$  [12, 14].

Here, we focus on recursive blocked algorithms for solving triangular periodic matrix equations, i.e., the matrix sequences  $A_k$  and  $B_k$  for  $k = 1, \ldots, p$ are assumed to be in *periodic real Schur form* (PRSF) [2, 6]. This means that p-1 of the matrices in each sequence are upper triangular and one matrix in each sequence, say  $A_r$  for  $A_k$  and  $B_s$  for  $B_k$ ,  $1 \le r, s \le p$ , is quasi-triangular. The products of conforming diagonal blocks of the matrix sequences  $A_k$  and  $B_k$  contain the eigenvalues of the matrix products  $A_1A_2\cdots A_p$  and  $B_1B_2\cdots B_p$ , respectively, where the  $1 \times 1$  and  $2 \times 2$  blocks on the main block diagonal of  $A_r$  and  $B_s$  corresponds to the real and complex conjugate pairs of eigenvalues of these matrix products. Triangular matrix equations appear naturally in estimating the condition numbers of matrix equations and different eigenspace computations, including decoupling and stability analysis. To solve a triangular matrix equation is also a major step in the classical Bartels-Stewart method [1]. Periodic Sylvester-type matrix equations also appear in the context of eigenvalue reordering for computation and condition estimation of periodic invariant (deflating) subspaces of a matrix (pair) sequence [4, 5].

# 2 Recursive algorithms for periodic triangular matrix equations

Our research includes recursive blocked algorithms for solving the most common one-sided and two-sided triangular periodic Sylvester-type matrix equations. In this contribution, we focus on one-sided equations, namely the periodic continuous-time standard Sylvester and Lyapunov equations and a periodic generalized coupled Sylvester equation (see Table 1).

By using and reusing recursive templates, we can solve all matrix equations listed in Table 1 utilizing only a small set of subroutines. By this, we mean that, e.g., the PLYCT problem can be largely solved by the PSYCT routine. Therefore, the efforts of optimizing the implementation can be concentrated on a few core routines.

Name	Mnemonic	Matrix equation
Periodic standard Sylvester	PSYCT	$\begin{cases} A_k X_k - X_{k+1} B_k = C_{k+1} \\ A_p X_p - X_1 B_p = C_1 \end{cases}$
Periodic standard Lyapunov	PLYCT	$\begin{cases} A_k X_k + X_{k+1} A_k^T = C_{k+1} \\ A_p X_p + X_1 A_p^T = C_1 \end{cases}$
Periodic generalized coupled Sylvester	PGCSY	$\begin{cases} A_k X_k - X_{k+1} B_k = C_{k+1} \\ A_p X_p - X_1 B_p = C_1 \\ A_k X_k + X_{k+1} A_k^T = C_{k+1} \\ A_p X_p + X_1 A_p^T = C_1 \\ A_k X_k - Y_k B_k = C_{k+1} \\ D_k X_{k+1} - Y_k E_k = F_{k+1} \\ A_p X_p - Y_p B_p = C_1 \\ D_p X_1 - Y_p E_p = F_1 \end{cases}$

**Table 1.** Considered one-sided periodic Sylvester-type matrix equations. Here, p is the periodicity of the matrix sequences and  $1 \le k < p$ .

The periodic matrix sequences are stored as 3-dimensional arrays, where the third dimension is the periodicity p of the matrix equation. The successive recursive splittings are performed on the 3-dimensional arrays explicitly, leading to new types of data locality issues.

Besides high-performance issues of the new algorithms, we also investigate accuracy issues including the solution of ill-conditioned periodic matrix equations and the solution of matrix equations with a large periodicity compared to the matrix dimensions. An important difference between non-periodic and periodic Sylvester-type matrix equations is the hard data dependency introduced from the periodicity of the problem. We discuss the impact of this data dependency and how to avoid degradation in speed from it. This is based on work done with the superscalar kernels that were developed for the RECSY library [7–9].

Different implementation issues are discussed, including when to end the recursion and the design of optimized and robust superscalar kernels for solving leaf-node triangular periodic matrix equations efficiently. Using the superscalar kernels, the new algorithms are able to solve periodic Sylvester-type equations with large periods but with small dimensions of the matrices (M, N). Uniprocessor and SMP parallel performance and accuracy results of our recursive blocked algorithms are presented.

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