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Stabilized Nitsche Cut-Elements for Wave Propagation

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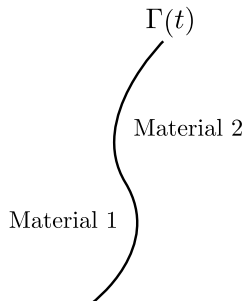
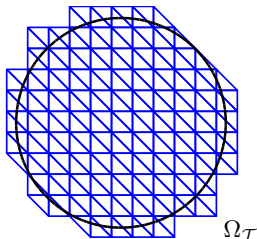
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Introduction



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- ▶ Cut elements - Immersed method
- ▶ Domain Ω
- ▶ Uniform background mesh
- ▶ Application: Interface moving with time
 - ▶ Distorted mesh
 - ▶ Remeshing expensive



Main Goal



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- ▶ Immersed method for Wave Propagation
- ▶ Focus: Scalar wave eq
- ▶ Future: Elastic wave eq
- ▶ High order more effective

Problem

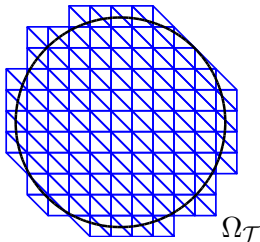


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- ▶ Wave equation

$$\begin{cases} \ddot{u} & = \nabla^2 u + f(\mathbf{x}, t) & \mathbf{x} \in \Omega \\ u|_{\Gamma_D} & = g_D(\mathbf{x}, t) \\ \frac{\partial u}{\partial n} \Big|_{\Gamma_N} & = g_N(\mathbf{x}, t). \end{cases}$$

- ▶ FEM, Based on Burman and Hansbo [2012]
- ▶ Solve for dofs of $\Omega_{\mathcal{T}}$
- ▶ Weak boundary conditions by Nitsche



$$(\ddot{u}, v)_{\Omega} + a(u, v) = L(v) \quad \forall v \in V,$$

$$a(u, v) = (\nabla u, \nabla v)_{\Omega} - \left\langle \frac{\partial u}{\partial n}, v \right\rangle_{\Gamma_D} - \overbrace{\left\langle u, \frac{\partial v}{\partial n} \right\rangle_{\Gamma_D} + \beta_D \langle u, v \rangle_{\Gamma_D} + \beta_N \left\langle \frac{\partial u}{\partial n}, \frac{\partial v}{\partial n} \right\rangle_{\Gamma_N}}^{\text{Nitsche penalty terms}}$$

$$L(v) = (f, v)_{\Omega} + \overbrace{\left\langle g_D, \beta_D v - \frac{\partial v}{\partial n} \right\rangle_{\Gamma_D}}^{\text{Nitsche penalty terms}} + \left\langle g_N, v + \beta_N \frac{\partial v}{\partial n} \right\rangle_{\Gamma_N}.$$

Ill-conditioning



- ▶ Want to calculate quantities of type $(\phi_i, \phi_j)_\Omega$, $(\nabla \phi_i, \nabla \phi_j)_\Omega$, Ill-conditioned
- ▶ Stabilization, j , Burman and Hansbo [2012], Massing et al. [2014]

Weak fom: $(\ddot{u}, v)_\Omega + a(u, v) = L(v) \quad \forall v \in V$,

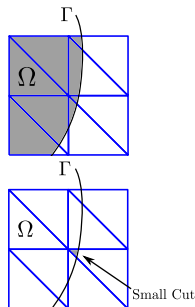
FEM: $M(\ddot{u}_h, v_h) + A(u_h, v_h) = L(v_h) \quad \forall v_h \in V_h$

$$M(\ddot{u}_h, v_h) := (\ddot{u}_h, v_h)_\Omega + \gamma_M h^2 j(\ddot{u}_h, v_h)$$

$$A(u_h, v_h) := a(u_h, v_h) + \gamma_A j(u_h, v_h)$$

$$\|v_h\|_{\Omega_\mathcal{T}}^2 \leq C_M M(v_h, v_h) \leq C_M \|v_h\|_{\Omega_\mathcal{T}}^2$$

$A(u_h, v_h)$ – coercive



Stabilization



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- Estimate, by Taylor expansion

$$\|v\|_{T_1}^2 \leq C \left(\|v\|_{T_2}^2 + \sum_{q=1}^p \frac{1}{q!^2} \frac{h^{2q+1}}{2q+1} \langle [\partial_{\mathbf{n}}^q v], [\partial_{\mathbf{n}}^q v] \rangle_F \right)$$

$$\partial_{\mathbf{n}}^q v = \sum_{|\alpha|=q} \frac{q!}{\alpha!} D^\alpha v \mathbf{n}^\alpha$$

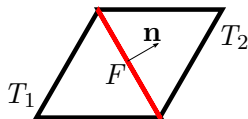
$$\alpha = (\alpha_1, \alpha_2, \dots, \alpha_d)$$

$$|\alpha| = \alpha_1 + \alpha_2 + \dots + \alpha_d$$

$$D^\alpha = \frac{\partial^{\alpha_1}}{\partial x^{\alpha_1}} \frac{\partial^{\alpha_2}}{\partial x^{\alpha_2}} \dots \frac{\partial^{\alpha_d}}{\partial x^{\alpha_d}}$$

$$\mathbf{n}^\alpha = n_1^{\alpha_1} n_2^{\alpha_2} \dots n_d^{\alpha_d}$$

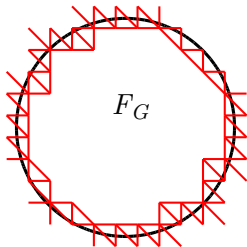
$$\alpha! = \alpha_1! \alpha_2! \dots \alpha_n!$$



- ▶ Stabilization term j on faces F_G

$$j(u, v) = \sum_{F \in F_G} \sum_{q=1}^p h^{2q-1} \langle [\partial_{\mathbf{n}}^q u], [\partial_{\mathbf{n}}^q v] \rangle_F$$

$$\text{for } p = 1 : j(u, v) = \sum_{F \in F_G} \langle h[n \cdot \nabla u_h], [n \cdot \nabla v_h] \rangle_F$$





$$M(\ddot{u}_h, v_h) + A(u_h, v_h) = L(v_h) \quad \forall v_h \in V_h$$

- ▶ Discretizes to

$$\mathcal{M}\ddot{\xi} + \mathcal{A}\xi = \mathcal{L}(t)$$

- ▶ \mathcal{M} sym pos def $\Rightarrow \mathcal{M}^{\frac{1}{2}}$ well defined

$$\ddot{\eta} + \mathcal{B}\eta = \mathcal{F}(t)$$

where

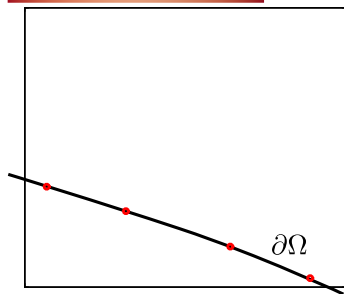
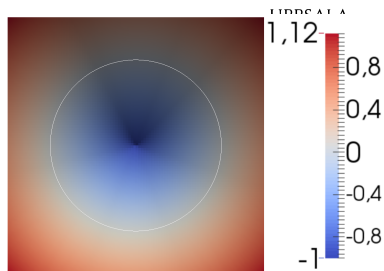
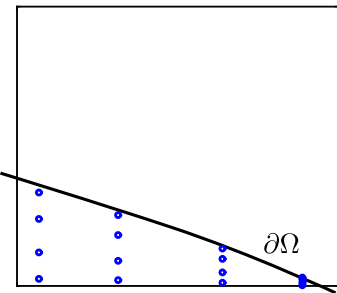
$$\eta = \mathcal{M}^{\frac{1}{2}}\xi, \quad \mathcal{B} = \mathcal{M}^{-\frac{1}{2}}\mathcal{A}\mathcal{M}^{-\frac{1}{2}}$$

- ▶ Real wave-numbers!

Quadrature



- ▶ Levelset
 - ▶ $\partial\Omega$ def by zero contour
- ▶ Quadrature
 - ▶ Use algorithm from Saye [2015]
 - ▶ Hyperrectangels
 - ▶ Build Quadrature from levelset
 - ▶ Implicit function theorem
 - ▶ 1D-rootfinding



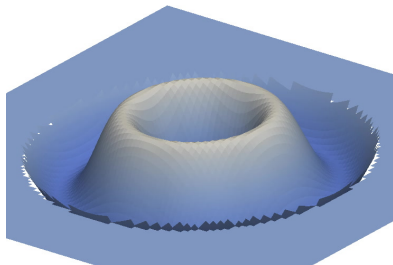
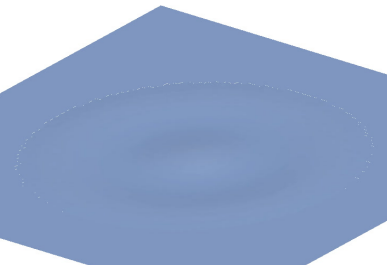
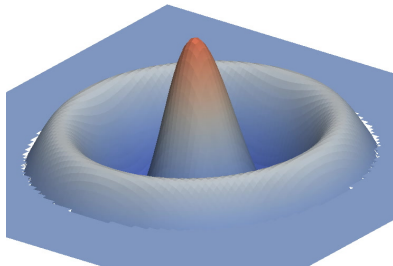
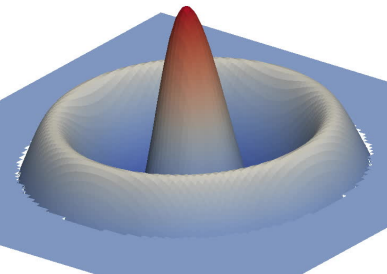
Membrane

- ▶ Circular domain
- ▶ $u|_{\partial\Omega} = 0$

- ▶ $u|_{t=0} = J_0\left(\alpha_n \frac{\|\mathbf{x}\|}{R}\right)$
- ▶ $\dot{u}|_{t=0} = 0$



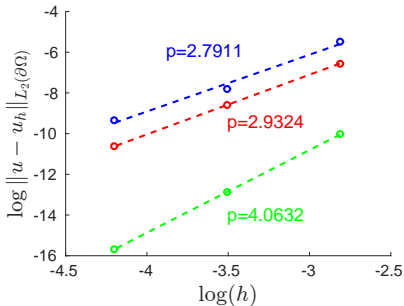
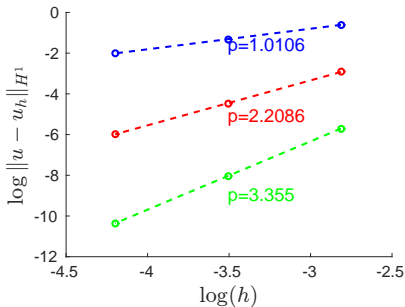
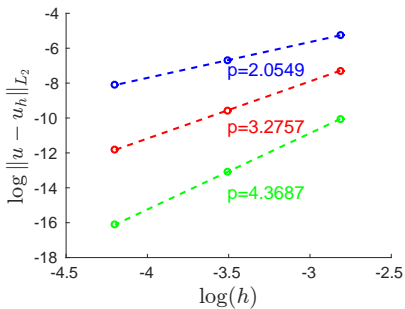
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Convergence Q1-Q3 elements



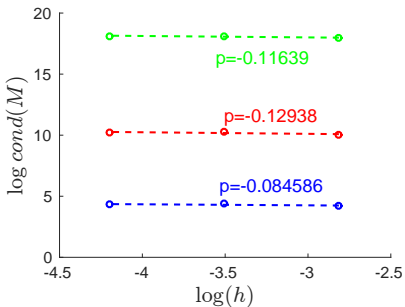
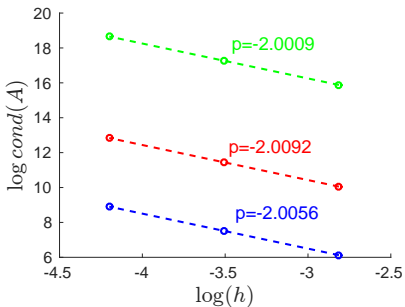
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Condition Numbers Q1-Q3 elements



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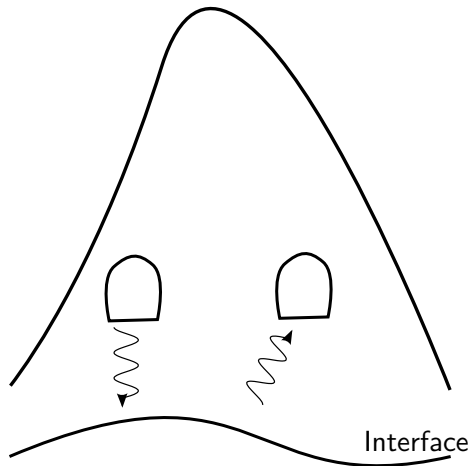


Future Application



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- ▶ Elastic wave equation
- ▶ Unknown interface geometry
- ▶ Find shape by optimization



Summary



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- ▶ Cut elements for wave propagation
- ▶ Weak boundary condition by Nitsche
- ▶ Stabilizing terms
- ▶ Tested up to 4th order convergence
- ▶ Plans for elastic wave equation



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Thank you!

Erik Burman and Peter Hansbo. Fictitious domain finite element methods using cut elements: II. A stabilized Nitsche method. *Applied Numerical Mathematics*, 62(4):328–341, 2012. ISSN 0168-9274. doi: 10.1016/j.apnum.2011.01.008. URL <http://dx.doi.org/10.1016/j.apnum.2011.01.008><http://www.sciencedirect.com/science/article/pii/S0168927411000298>.



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